RECTILINEAR DISPLACEMENT TRANSDUCER WITH CYLINDRICAL CASE



PC

Principal characteristics

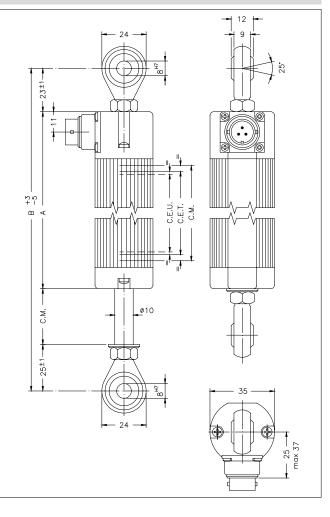
- The transducer is designed to satisfy extreme applicative demands in terms of mechanical strength.
- The 10 mm diameter rod, large steel joints, and reinforced structure make this series mechanically ideal for metalworking, woodworking, and ceramics.
- Installation is simplified by the lack of electrical signal variation at output outside theoretical electrical stroke.
- The structure based on self-aligning and weight-bearing ball joints permits assembly with free movement of the transducer axle.

TECHNICAL DATA

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Useful electrical stroke (C.E.U.)	from 50 to 1300 mm (for intermediate strokes see table "Electri- cal / Mechanical Data")
Independent linearity (within C.E.U.)	± 0,05%
Resolution	Infinite
Repeatability	0.01 mm
Protection	IP65
Displacement speed	≤ 5 m/s
Displacement force	≤ 15 N
Life	 > 25x10^e m strokes,or > 100x10^e operations, whichever is less (within C.E.U.)
Vibrations	52000Hz, Amax =0.75 mm amax. = 20 g
Shock	50 g, 11ms.
Tolerance on resistance	±20%
Recommended cursor current	< 0.1 µA
Maximum cursor current	10mA
Max. applicable voltage	60V
Electrical isolation	>100MΩ at 500V=, 1bar, 2s
Dielectric strength	< 100µA at 500V~, 50Hz, 2s, 1bar
Dissipation at 40°C (0W at 120°C)	3W
Actual Temperature Coefficient of the output voltage	<= 5 ppm/°C
Working temperature	-30+100°C
Storage temperature	-50+120°C
Case material	Anodised aluminium Nylon 66 G
Control rod material	Stainless steel AISI 303
Fixing	2 selfloading and selfaligning ball-joints

MECHANICAL DIMENSIONS



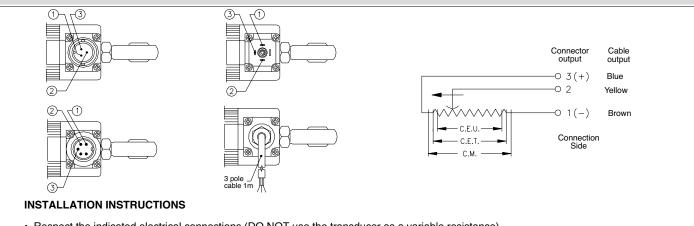
Important: all the data reported in the catalogue linearity, lifetime, temperature coefficient are valid for a sensor utilization as a ratiometric device with a max current across the cursor Ic $\leq 0.1 \ \mu$ A.

MECHANICAL / ELECTRICAL DATA

MODEL		50	75	100	130	150	175	200	225	275	300	360	375	400	450	500	600	750	800*	850*	950*	1300*
Useful electrical stroke (C.E.U.) +3/-0	mm	50	75	100	130	150	175	200	225	275	300	360	375	400	450	500	600	750	800	850	950	1300
Theoretical electrical stroke (C.E.T.) ± 1	mm			C.E.l	J. + 3			C.E.U. + 4			364	380	406	457	508	609	762	813	863	965	1320	
Resistance (C.E.T.)	kΩ		5 10																			
Mechanical stroke (C.M.)	mm	C.E.U. + 9				C.E.U. + 10			371	386	412	463	518	619	772	823	873	975	1330			
Case length (A)	mm	C.E.U. + 130.5				C.E.U. + 131.5			497.5	513.5	539.5	590.5	665.5	766.5	919.5	970.5	1020.5	1122.5	1477.5			
Min. distance between ball- joints (B)	mm	C.E.U. + 179				C.E.U. + 180			546	562	588	639	715	815	968	1019	1069	1171	1526			

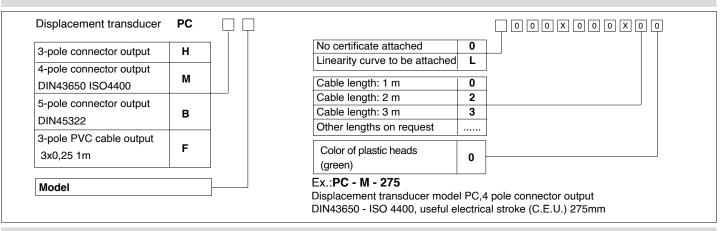
* = Only for vertical installations

ELECTRICAL CONNECTIONS



- Respect the indicated electrical connections (DO NOT use the transducer as a variable resistance)
- When calibrating the transducer, be careful to set the stroke so that the output does not drop below 1% or rise beyond 99% of the supply voltage.

ORDER CODE



OPTIONAL ACCESSORIES

4-pin 90° radial female PCM connector INDUSTRIAL STANDARD EN175301 spacing 9,4 mm IP65 PG7 for cable ø4 - ø6 mm	CON008
3-pin axial female PCH connector IP40 clamp for wire ø4 - ø6 mm	CON002
5-pin axial female PCB connector DIN43322 IP40 clamp for wire ø4 - ø6 mm	CON011
5-pin axial female PCB connector DIN43322 IP65 clamp PG7 for wire ø4 - ø6 mm	CON012
5-pin 90° radial female PCB connector DIN43322 IP40 clamp for wire ø4 - ø6 mm	CON013

GEFRAN spa reserves the right to make any kind of design or functional modification at any moment without prior notice



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