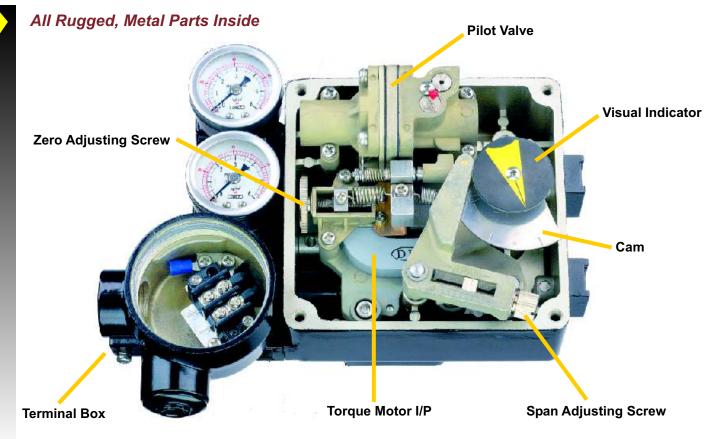
### A Solid Workhorse You Can Depend On For Consistent, Reliable Control

Moniteur's Series 40 Pneumatic (3-15psi) and Series 41 Electro-Pneumatic (4-20mA) positioners are advanced control devices which provide unparalleled stability in difficult environments.

- ➤ Rugged Aluminum Housing with a triple corrosion-resistant interior and exterior coating stands up to harsh environments
- ➤ Reduced Bleed Pilot Valve reduces air consumption by more than 50%
- ➤ No Spool Valves are used for air delivery, improving resistance to dirty plant air
- ➤ Unique Magnetic 4-20 mA I/P automatically compensates for supply pressure, atmospheric pressure and ambient temperature changes, and is unaffected by EMF. The vibration resistant design has no resonance effects from 5-200Hz
- Precise Calibration with simple SPAN and ZERO adjustments.
- ➤ Precision Zero-Hysteresis Coupling System for NAMUR actuators provides superior accuracy and repeatability by eliminating "slop".
- > Stainless Steel Gauges Standard
- ➤ Optional Limit Switches and 4-20mA Feedback
- ➤ Each Positoner Performance Tested Test results included in the box with each positioner guarantee consistent performance.





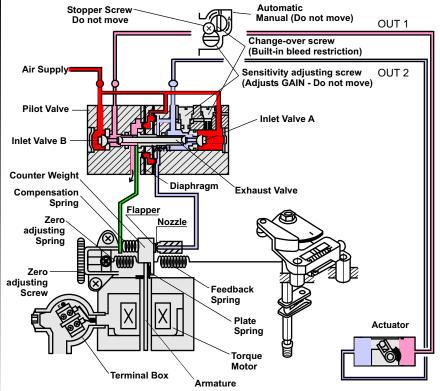
#### Specifications -3-15 psi Pneumatic

Input Signal	3 - 15 psig Split Range Standard
Impedance	N/A
Stroke Range:	0 - 90°
Supply Range:	20 to 100 PSIG
Air Delivery:	7 SCFM
Air Consumption:	0.26 SCFM
Operating Temperature:	-4° to +158° F
Linearity	+/- 1%
Hysteresis	1% max.
Sensitivity	+/- 0.5%
Repeatability	+/- 0.5%
Pneumatic Connections:	1/8 NPT - Gauge Ports 1/4 NPT - Supply / Outlet
Enclosure:	Designed to NEMA 4, 4X
Enclosure Weight:	Approx. 4.8 lbs.

#### Specifications - 4-20 mA Electro-Pneumatic

Input Signal	4 - 20 mA @ 24 VDC Split Range Standard
Impedance	250 +/- 15 ohms
Stroke Range:	0 - 90°
Supply Range:	20 to 100 PSIG
Air Delivery:	7 SCFM
Air Consumption:	0.15 SCFM
Operating Temperature:	-4° to +158° F
Linearity	+/- 1%
Hysteresis	1% max.
Sensitivity	+/- 0.5%
Repeatability	+/- 0.5%
Pneumatic Connections:	1/8 NPT - Gauge Ports 1/4 NPT - Supply / Outlet
Enclosure:	Designed to NEMA 4, 4X
Enclosure Weight:	Approx. 6.5 lbs.

#### Principle Of Operation - Rotary Positioner



As the signal current from the controller increases, the plate spring of the torque motor works as a pivot. As the armature receives the rotary torque in the counter-clockwise direction, the counter-weight is pushed to the left, the clearance between the nozzle and the flapper will increase, and the nozzle back pressure will decrease. As a result, the exhaust valve of the pilot valve moves to the right, and the output pressure of OUT1 increases (as OUT 2 decreases) to move the actuator.

The movement of the actuator in turn rotates the feedback shaft and spring. The actuator stays in the position where the spring force is balanced with the force generated by the input current in the torque motor. The compensation spring is for direct feedback of the motion of the exhaust valve, and is connected to the counter weight to enhance the stability of the loop. The zero point is adjusted by changing the zero adjustment spring tension.

### Intelligent Part Number System











**Description** 





Code

<u>Description</u>	Code
Series: Pneumatic Electro-Pneumatic	40 41
Shaft: Rotary NAMUR	N
Electrical Ratings Standard (Pneumatic Only) Ex md IIT6 (Standard for 4-20) Intrinsically Safe	S E A

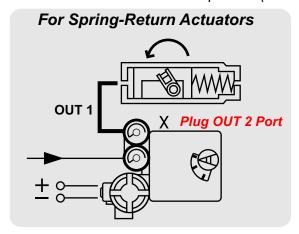
<u>Description</u>	Code
Pilot Valve Standard Orifice Small Orifice Kit Included	1
Position Feedback None 4-20 mA 2 SPDT Limit Switches 4-20 MA + Limit Switches	N T S TS

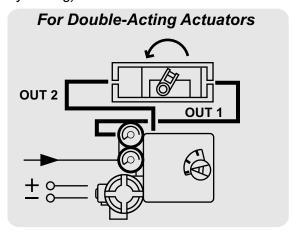
Gauges Stainless Steel (Standar	rd) S
Indication: Flat Dial	F
NAMUR Brackets	
80x30x20	BKT-FS1206
80x30x30	BKT-FS1516
130x30x30	BKT-FS1306
130 x 30 x 50	BKT-FS1616

Positioners include: linear feedback cam, 7 SCFM spool valve and gauges

#### **Piping Configuration - Reverse Acting**

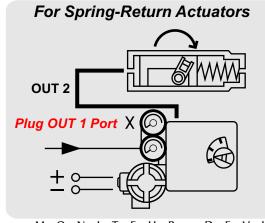
- ➤ Actuator Stem Rotates Counter-Clockwise As Input Signal Increases
- ➤ Cam should be set with RA upwards (standard factory setting)

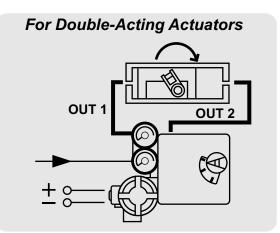




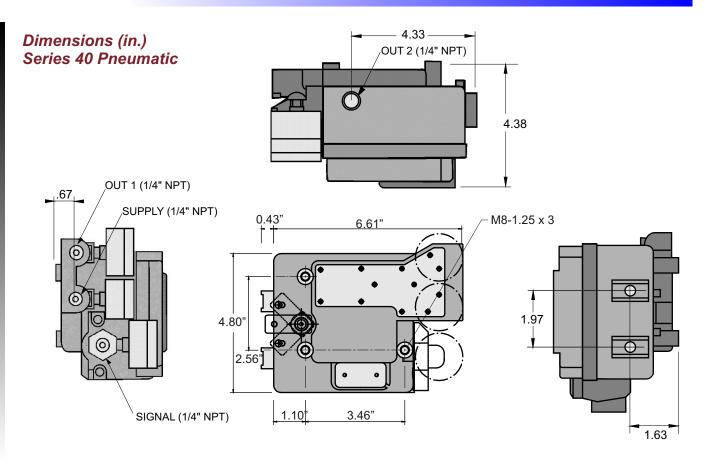
### Piping Configuration - Direct Acting

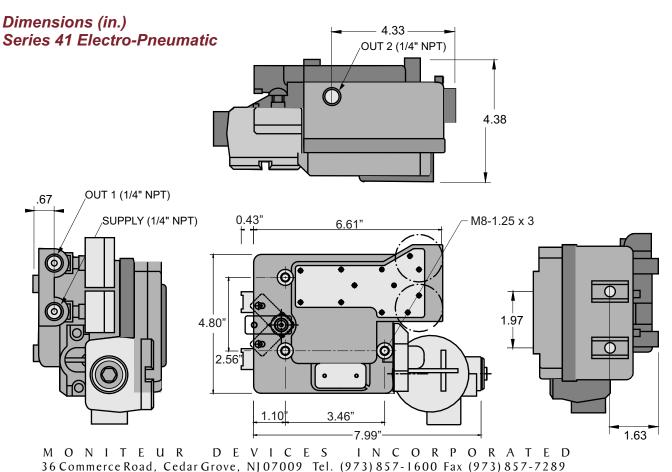
- ➤ Actuator Stem Rotates Clockwise As Input Signal Increases
- ➤ Cam should be set with DA upwards





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