

Motion & Motor Control Solutions

C-2271

DUAL AXIS DRIVE

BENEFITS

Dual linear axis USB 2.0 setup and diagnostics interface Quadrature or +/- 10V DC analog feedback Brushed, brushless, stepper control Application specific parameters stored in EEPROM Sinusoidal or trapezoidal operation 50W continuous Passive cooling Overtemperature protection

APPLICATIONS

Optics positioning Linear motor stages Laboratory test equipment Small brushless DC motors

TECHNICAL SPECIFICATIONS

ELECTRICAL (DRIVES)

SUPPLY VOLTAGE

Unipolar: 18V to 48V (±10%) Absolute max: 52V

EQUIVALENT MOTOR VOLTAGE

Up to ±43V*

MAXIMUM OUTPUT CURRENT

See SOA chart

COMMAND INPUT: ±10V TORQUE GAIN: 0.05 A/V to 0.2 A/V BANDWIDTH: 5 kHz**

ELECTRICAL (CONTROLLER)

SUPPLY VOLTAGE

Minimum: 20VDC Nominal: 24VDC Maximum: 28VDC

SUPPLY CURRENT: 0.5A Minimum: 0.5A Maximum: 1.0A

5V SUPPLY CURRENT OUTPUT: 800mA 12V SUPPLY CURRENT OUTPUT: 50mA -12V SUPPLY CURRENT OUTPUT: 50mA

CONNECTIONS

AXIS (0,1) ENCODER INPUT (J1,J2) 26-Pin HD, female, vert, D Shell

AXIS (0,1) HALLS (J3, J4) 9-Pin female, vert, D Shell

AXIS (0,1) MOTOR (J5, J6) 4-Pin Mini Mate-n-Lock, vert, receptacle

DC POWER IN (J7)

6-Pin Mini Mate-n-Lock, vert, receptacle USB (J8)

Type B shielded, receptacle **DEBUG (J9)** 9-Pin, male, vert, D Shell

MECHANICAL

LENGTH: 7.00 in (17.78 cm) WIDTH: 5.00 in (12.70 cm) HEIGHT: 2.00 in (10.16 cm) WEIGHT: 3 lbs (1.36 kg) MOUNTING: (4) 6-32 screws, captive



MAXIMUM ALTITUDE

6,560FT (2000M)

TEMPERATURE (ambient)

Normal operation: +5°C to +40°C Storage: -20°C to +60°C Heatsink: +75°C maximum

HEAT DISSIPATION (@25°C)

Continuous: 50W

Peak: See SOA chart

AIRFLOW

35°C ambient, measured at air inlet, to heatsink

HUMIDITY

Operating: 10% to 70%, non-condensing Storage: 10% to 95%, non-condensing

POLLUTION DEGREE 2

*dependent upon motor load **into a 2.5 mH load

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DUAL AXIS LINEAR DRIVE, PROVIDING SMOOTH POWER TO BRUSHLESS MOTORS

The Trust Automation C-2271 Dual Axis Linear Drive is an intelligent three phase servo motor amplifier designed to drive a brushless motor with up to 50W of power. This device is an excellent solution for small rotary or linear brushless motors in high precision positioning applications and systems where low electrical noise operation is essential. The C-2271 is optimized for both sinusoidal and trapezoidal output. Unlike standard PWM (switcher-type) amplifiers, the trapezoidal output is smoothed to minimize cogging. This flexibility enables the engineer to provide a clean linear solution for the most demanding motion control applications. The C-2271 uses a three-character programming language, providing over one hundred available commands to handle even the most demanding applications. The 104.2 µs servo update rate is ideal for linear motor axes requiring fast settling times. The dual processor design optimizes performance by splitting the tasks between command execution, host communication and general I/O. This advanced design delivers peak performance while reducing your development time and shortening your time to market. The C-2271 is feature rich and flexible, suitable for most medium to high end applications.

SPECIFICATIONS

FEATURE

Encoder Input Frequency Min Position Loop Update Rate Max Position Loop Update Rate Max Communication Rate Step/Direction, Pulse Frequency Sinusoidal Communication Rate Analog Feedback Resolution DAC Resolutions, 2/Axis Optional Position Range Velocity Range Acceleration Range Jerk Range Motion Profile Modes

Filter Gain Types

Filter Terms

Position Error Size Dedicated I/O, Per Axis

DESCRIPTION

8.0 M counts/sec 0.1 kHz 1-Axis: 9.7 kHz, 2-Axis 6.5 kHz 10.0 kHz 5.0 MHz 100 µs 14 Bits Min: 12 Bits Max: 16 Bits ± 2,147,483,648 counts per move (32 bit) ± 655,360,000 counts / sec ± 655,360,000 counts / sec 2 ± 8,000,000,000,000 counts / sec ³ Trapezoidal, Point to Point & Interpolated S-curve, Point to Point Velocity Contouring **Electronic Gearing Custom Contouring** Home Filter Set Stopped Filter Set Motion Filter Set (Kp) Proportional, (Ki)Integral, (Kd)Derivative (IL)Integral Limit, (TL) Torque Limit, (DS)Derivative Sub Sampling (AF)Acceleration and (VF)Velocity Feed Forward, (PW)Position Window (SH)Parameter Global Scale + 2,147,483,647 to - 2,147,483,648 Encoder Counts Positive Limit, Negative Limit Home Sensor **Drive Enable** User Input



SAFE OPERATING AREA



Drive Voltage (V) = Supply (V) - Winding (V)

MECHANICAL DRAWING



