LM10 Incremental Magnetic Encoder

The LM10 is a non-contact high-speed magnetic encoder designed for linear or rotary motion sensing in harsh environments. It features a compact readhead that rides at up to 1.0 mm from the self-adhesive magnetic scale or ring.

Simple to install, the LM10 features a set-up LED and wide installation tolerances. The encoder comes in digital or analogue output variants and offers a range of customer selectable resolutions from 0.244 μ m to 250 μ m.



Features and benefits

- Customer selectable resolutions
- High speed operation
- Excellent dirt immunity to IP68
- Linear or rotary position sensing
- Unique bidirectional reference mark
- Non-contact and wear-free measuring principle
- ► CE compliant, including RoHS
- Highly resistant to shock, vibration and pressure



ROBUST UNIQUE REFERENCE MARK

WEAR-FREE MEASURING PRINCIPLE DATA SHEET LM10D01_16

General information

Engineered for extreme service, the solid-state LM10 linear encoders operate from –10 °C to +80 °C, have water-proof sealing to IP68 and are highly resistant to shock, vibration and pressure. The robust magnetic scale and ring are also resistant to various chemicals commonly found in industry. The non-contact, frictionless design eliminates wear and reduces hysteresis.

Choose your LM10 system

The robust LM10 readhead is compatible with the RLS MS10 incremental scale as well as the RLS axial and radial rings. You can select the length of the MS scale up to 150 m. There is also a wide range of axial and radial incremental rings available.



Encoder variants

LM10



LM10 readhead comes with analogue 1 Vpp, incremental quadrature RS422, Push-pull or Open collector outputs.

LM10 + cable with flexible stainless-steel conduit



LM10 with cable with flexible stainless-steel conduit which is excellent for harsh environments. It comes with standard LM10 outputs.



Storage and handling

All data given below refer to the readhead only. Complete systems with magnetic scale or ring may have other limitations. For more information, see the MSD01, MR01D01 or MR02D02 data sheet at **<u>RLS Media center.</u>**

Storage temperature

–40 °C to +85 °C



IP protection

IP68









Readhead is ESD sensitive - handle with care.

Do not touch electronic circuit, wires or sensor area without proper ESD protection or outside of ESD controlled environment.



This encoder system is a high performance metrology product and must be handled carefully. The use of industrial tools during installation or exposure to strong magnets such as a magnetic base is not recommended as it carries the risk of damaging parts of the system which as a result might not perform in accordance with specifications.

Packaging

Each readhead is packed individually in antistatic bag, according to ESD protection measures.

Labeling



Label on the readhead contains: full PN, 6 digits long serial number and 2D code containing the serial number.

Dimensions

Dimensions and tolerances are in mm. Dimensions without tolerance values are in accordance with ISO 2768-m.



3D model available for download at **RLS Media center.**

General tolerances for linear dimensions according to ISO 2768 m					
Tolerance class	up to 6	6-30	30-120		
m (medium)	±0.1	±0.2	±0.3		





LM10 readhead with cable with stainless-steel protection tube

Max. length of cable with flexible stainless-steel conduit is 10 m.

Installation instructions

The readhead LED must be green at all measuring length positions. Otherwise, the installation is not performed correctly. The 0.1 mm to 1.0 mm thick plastic spacer (shim) can be used to facilitate installation. For optimal installation, the recommended thickness of the shim is 0.3 mm. After mounting the magnetic scale, place the plastic shim and the readhead on the magnetic scale. Make sure that the readhead, shim and magnetic scale are in full contact.

Improper mounting of the magnetic scale and readhead can impair the function of the magnetic encoder system and lead to total failure.







Images are for illustration purposes only. Valid for all versions.

Position of installation holes

Recommended use of M3 fasteners with washers. For more information, see **Table of recommended fastener tightening** torques at RLS Media center.

- The magnetic encoder system must be installed and mounted in strict compliance with the dimensions and tolerances given on **page 4**. All permissible distance and angle tolerances must be strictly complied according to the mounting instructions found at MSD01, MR01D01 or MR02D02 data sheet at **RLS Media center**.
- It is important that the space between the readhead and the magnetic scale is maintained over the entire measuring range.
- The magnetic encoder system must be used in accordance with the specified degree of protection. The following factors must be taken into account: IP protection class, operating temperature, external magnetic field, humidity level, mechanical load and EMC compatibility.
- The magnetic encoder system is sensitive to the external magnetic fields. The magnitude of the influence on the
 magnetic encoder system depends on the magnitude and direction of the external magnetic field. In particular, the
 rapidly changing stray magnetic fields affect the system and can alter its function. Magnetic field strength within 1 mT
 reduces the accuracy of the system. Field strengths greater than 1 mT will cause the system to malfunction and as a result
 the readhead will report an incorrect position with the red color LED. Magnetic field strengths greater than 25 mT will
 cause irreversible damage to the magnetic scale or ring and will have to be replaced.

Cable installation



Technical specifications

Dimensions and tolerances are in mm. Dimensions without tolerance values are in accordance with ISO 2768-m.

System data		
Pole length		2 mm
Maximum measur	ing length	50 m (up to 150 m per request)
System accuracy Linear application		±10 μm/m / ±20 μm/m / ±40 μm/m
	MS magnetic scale	Different accuracy grades of MS magnetic scale are available.
		Refer to MSD01 available at <u>RLS Media center.</u>
	Rotary application	Axial: Refer to MR01D01 available at RLS Media center.
		Radial: Refer to MR02D02 available at RLS Media center.
Hysteresis		< 3 µm at 0.3 mm ride height
Repeatability		< 1 µm at 25°C
Reference mark		Unique / Periodic / DCRM (information about distance coded ref. mark can
		be found in the MSD01 at RLS Media center).
Resolution		Max. 13 bit (~0.244 μ m) For details refer to the Table of available
		resolutions.
Maximum speed	Linear application	Refer to MSD01 available at RLS Media center.
	Rotary application	Axial: Refer to MR01D04 available at RLS Media center.
		Radial: Refer to speed calculator available at <u>RLS website.</u>

Electrical data

For electrical data see specific output type on pages 12 to 15

Mechanical data

Mass	Readhead	23 g
Material	Readhead	Die-cast, Zamak-5

Environmental data

Temperature	Operating	-10 °C to +80 °C (-20 °C to +85 °C if cable under non-dynamic conditions)
	Storage	-40 °C to +85 °C
Environmental sea	ling	IP68 (according to IEC 60529)*
EMC Immunity		IEC 61000-6-2
EMC Emission		IEC 61000-6-4
Vibrations (55 Hz to	o 2000 Hz)	300 m/s² (IEC 60068-2-6)
Shocks (6 ms)		300 m/s² (IEC 60068-2-27)
External magnetic	field during operation	1 mT

*Limited by the connector.

Cable

Туре	PUR high flexible cable, drag-chain compatible, double-shielded			
Number of wires	8	12**		
Outer diameter	4.2 mm ±0.2 mm	4.5 mm ±0.2 mm		
Jacket material	Extruded polyurethane (PUR)			
White wire	0.14 mm², 26 AWG, 0.13 Ω/m	- 0.00 mm ² 20 AN/C 0.22 O/m		
Other wires	0.05 mm², 30 AWG, 0.35 Ω/m	0.08 mm², 28 AwG, 0.23 Ω/m		
Durability	20 million cycles at 25 mm bend radius	20 million cycles at 50 mm		
		bend radius		
Weight	34 g/m nominal	38 g/m nominal		
Bend radius (internal radius)	Dynamic: 25 mm, static: 10 mm	Dynamic: 50 mm, static: 10 mm		
Dynamic torsion	Not allowed*			

*Cable is not torsion specified. A continuous torsion of the cable in a dynamic application could result in malfunctioning of the encoder system.

**Applied only for option with additional alarm output (for IA, IC; not available for PRG option).

Cable tolerances

LM10 with cable

LM10 with cable with stainless-steel protection tube

Cable length* [m]	Tolerance [mm]	Cable length* [m]	Tolerance [mm]
≤ 5	+50/-20	≤ 5	+70/-30
> 5 ≤ 10	+70/-30	> 5 ≤ 10	+100/-40
> 10 ≤ 30	+100/-40		

*Cable length without connector.



Electrical connections

		C. J	9 pin D type plug (<u>option A</u>)	15 pin D type plug (<u>option D</u>)	9 pin CPC connector (<u>option E</u>)	15 pin HD type plug (<u>option H</u>)	15 pin D type plug (<u>option L</u>)	9 pin D type plug (<u>option P</u>)	7 pin DIN EN60130-9 plug (option U)
		Colour							30
Function	Signal	(option <u>F</u>)							
_	Vdd	Brown	5	7	8	7	4	5	5
Power	GND	White	9	2	7	2	12	1	1
	A / V ₁	Green	4	14	1	14	9	2	3
Incremental	A- / V ₁ -	Yellow	8	6	4	6	1	6	-
/ analogue signals	B / V ₂	Blue	3	13	2	13	10	4	4
	B- / V ₂ -	Red	7	5	5	5	2	8	-
Reference	Z / V ₀	Pink	2	12	3	12	3	3	6
signals	Z- / V ₀ -	Grey	6	4	6	4	11	7	-
	E	Violet	-	11	-	11	-	-	-
Alarm	E-	Black	_	3	_	3	-	-	-
<u>al : 11</u>	Inner	-	1	15	7	15	15	9	-
Shield	Outer	-	Case	Case	9	Case	Case	Case	Case

Shield connection

Figure below shows a recommended shield termination in order to ensure electromagnetic compatibility.



Housing of the encoder is galvanically connected with the housing of the connector via the cable outer shield. The encoder system must be correctly integrated to achieve EMC compliance. In particular, attention to shielding arrangements is essential.

Response time

	LM10AV	LM10IB	LM10IC_02*	LM10IA_02*	LM10IA	LM10IC
Set-up time	10 ms	10 ms	10 ms	10 ms	10 ms	10 ms
Interpolation conversion time	_	<250 ns	<250 ns	<250 ns	<250 ns	<250 ns
Transition time	<10 µs	<10 µs	<10 µs	<10 µs	<100 ms	<100 ms

*Shortened reaction time option.

Set-up time is the time needed for the encoder readhead to start reading the position information after power-on (see diagram 1). **Interpolation conversion time** is the time needed for the encoder readhead to convert the position information into an output signal.

Transition time is the time it takes the encoder readhead to switch from an alarm state to a valid output signal (see diagram 2).

Diagram 1: Set-up time



*In alarm state LED flashes red/green.

Diagram 2: Transition time



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Status indicator LED

After installation of the magnetic scale or ring (for MSD01, MR01D01 or MR02D02 data sheet refer to **RLS Media center**), the readhead can be easily adjusted on the machine using the set-up LED indicator.

		Er	ror output (s	pecial option 0	17)	
LED Signa	al	Status	IC (E)	IC (E-)	IA (E)	IA (E–)
	Green	Good signal strength/set-up	$U_{L} \leq 0.5 V$	$U_{_H} \ge 2.5 \text{ V}$	$U_{L} \leq 1.15 \text{ V}$	$U_{_H} \ge 3.45 \text{ V}$
•	Red	 Poor signal strength. Possible reasons: Incorrect readhead orientation. Readhead installation out of tolerance. Demagnetisation of measuring scale. Insufficient power supply voltage. 	U _H ≥ 2.5 V	$U_{L} \leq 0.5 V$	$U_{_{_{ m H}}} \ge 3.45 \text{ V}$	U _L ≤ 1.15 V
•••	Red/green flashing	 IB, IC_02, IA_02: poor signal strength Poor signal strength. Possible reasons: Incorrect readhead orientation. Readhead installation out of tolerance. Demagnetisation of measuring scale. Insufficient power supply voltage. 	Not applicable.			

The LED signal functions listed in the table above do not indicate non-optimal installation of the readhead, such as accuracy outside the specified range or improper operation of the reference mark.

Positive direction

Digital output signals – A leads B (magnetic scale is stationary)

Analogue output signals (1 \mathbf{V}_{pp}) – \mathbf{V}_1 leads \mathbf{V}_2



For more information, see the MSD01, MR02D02 or MR01D01 data sheet at **RLS Media center**.



Analogue output signals (1 V_{pp})

LM10AV

Specifications		
Power supply*	4.7 V to 7 V	
(voltage on readhead)	Reverse polarity protection	
Current consumption	<50 mA (without load)	
Voltage drop over cable	~13 mV/m (without load)	
	~54 mV/m (with 120 Ω load)	
Output signals	V ₁ , V ₂ , V ₀	
Sinusoidal period length	2 mm	
Sine / cosine signals	Amplitude	0.6 V_{pp} to 1.2 V_{pp}
	(with 120 Ω termination)	
	Phase shift	90° ± 0.5°
Reference signal	Amplitude	0.8 V_{pp} to 1.2 V_{pp}
	(with 120 Ω termination)	
	Position	45°
	Width	22.5°
Termination	Z_0 = 120 Ω between associated outputs	
Maximum cable length*	30 m	

*Please consider voltage drop over cable.

Timing diagram



Recommended signal termination





Incremental, Push-Pull output

LM10IA

Specifications					
Power supply*	4.7 V to 30 V				
(voltage on readhead)	Without reverse polarity protection				
Current consumption	<35 mA (without load)				
Voltage drop over cable	~13 mV/m (without load)				
Output signals	3 square-wave signals A, B, Z and their inverted signals A–, B–, Z–				
Reference signal	1 or more square-wave pulse Z and its inverted pulse Z–				
Signal level	For 30 V: $U_{\rm H} \ge 29.2$ V at $-I_{\rm H} = 30$ mA				
	$U_{L} \leq 0.5 \text{ V at } I_{L} = 30 \text{ mA}$				
	For 5 V: $U_{_{ m H}} \ge 4.2$ V at $-I_{_{ m H}}$ = 20 mA				
	$U_{L} \leq 0.5 \text{ V at } I_{L} = 20 \text{ mA}$				
Permissible load	$I_{L} \leq 50$ mA max. load per output				
	Outputs are protected against short circuit to 0 V and to +5 V				
Alarm	High impedance on output lines A, B, A–, B–				
	Special option 02: Alarm is not signaled by high impedance state of the A, B, /A, /B				
	signals				
	Special option 07: Alarm signal is output parallel as line driver signal				
Switching time - A, B, Z signals	For 24 V: t+ = t- < 380 ns (typ. 120 ns)				
(10 to 90 %)	For 5 V: t+ = t- < 200 ns (typ. 42 ns)				
	Measured at C _{LOAD} = 1000 pF				
Maximum cable length*	30 m				
	*If power supply voltage is <10 V, please consider voltage drop over cable.				

Timing diagram

Complementary signals are not shown



Recommended signal termination



V _{supply}	RL	I _{load}
5 V	250 Ω	20 mA
30 V	1 kΩ	30 mA

Incremental, Open Collector NPN

LM10IB

Specifications

Power supply	5 V to 30 V	
	Without reverse polarity protection	
Current consumption	<35 mA (without load)	
Voltage drop over cable	~13 mV/m (without load)	
	~54 mV/m (with 120 Ω load)	
Output signals	A, B, Z	
Reference signal	1 or more square-wave pulses Z	
Maximum load	10 mA	
Maximum cable length	See table below	

Edge separation [µm]	Maximum cable length [m]			
0.07	0.2	0.3	1	1.5
0.12	3	2.5	1	1
0.5	10	7	4	3
1	10	10	9	6
2, 4, 5, 10, 20	10	10	10	10
Power supply voltage [V]	5	12	24	30
R _L [Ω]*	500	1200	2400	3000

Encoder cable length and all other cable extensions should be taken into account.

*Recommended values. For higher values of R_i shorter cables should be used.

Timing diagram



Recommended signal termination





Incremental, RS422

LM10IC

Specifications

-	
Power supply*	4.7 V to 7 V
(voltage on readhead)	Reverse polarity protection
Current consumption	<35 mA (without load)
Voltage drop over cable	~13 mV/m (without load)
	~54 mV/m (with 120 Ω load)
Output signals	3 square-wave signals A, B, Z and their inverted signals A–, B–, Z–
Reference signal	1 or more square-wave pulse Z and its inverted pulse Z–
Signal level	Differential line driver according to EIA standard RS422:
	$U_{_{ m H}} \ge 2.5$ V at $-I_{_{ m H}}$ = 20 mA
	$U_{L} \leq 0.5 \text{ V at } I_{L} = 20 \text{ mA}$
Permissible load	$Z_0 \ge 100 \ \Omega$ between associated outputs
	$I_L \le 20$ mA max. load per output
	Capacitive load \leq 1000 pF
	Outputs are protected against short circuit to 0 V and to +5 V
	Only one output shorted at a time
Alarm	High impedance on output lines A, B, A–, B–
	Special option 02: Alarm is not signaled by high impedance state of the A, B, /A, /B
	signals**
	Special option 07: Alarm signal is output parallel as line driver signal
Switching time – A, B, Z signals	t+, t– < 30 ns (with 1 m cable and recommended input circuit)
(10 to 90 %)	
Maximum cable length*	30 m
	*Please consider voltage drop over cable.

** See diagrams 1 and 2 on page 10

Timing diagram

Complementary signals not shown



Recommended signal termination



Programming (for IC output only)

Readheads can be ordered preset to the required resolution or supplied so they can be programmed on the machine to the selected resolution. This programming is done by connecting the readhead to a computer via a programming interface **UPRG01**. The readhead must be ordered with the PRG option to use this function. For more information on the programming function of the LM10 readhead, see **UPRG01 Programming interface website**.

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Part numbering

	_	LM10	IC	01	0	C	A 1	0	F	00
Output type										
IA - Incremental Push-Pull outputs										
IB - Incremental, Open Collector NPN										
IC - Incremental, RS422										
Interpolation factor										
AV:										
000 - N/A										
IA, IB and IC:		020	100	(20,						
13B - 8192 (0.244 μ m) 09B - 512 (3. 12B - 4096 (0.488 μ m) D50 - 500 (4)	906 µm) um)	020 · D08 ·	- 100 - 80	(20 µm) (25 µm)						
11B - 2048 (0.977 μm) 005 - 400 (5	μm)	06B -	- 64	(31.250	µm)					
001 - 2000 (1 μm) D32 - 320 (6.	250 µm)	050	40	(50 µm)						
106 - 1600 (1.250 μm) 088 - 256 (7. 108 - 1024 (1.953 μm) 010 - 200 (10	813 µm)	05B · 04B ·	- 32 - 16	(62.500 (125 um	μm) 1)					
002 - 1000 (2 μm) D16 - 160 (12	2.500 µm)	03B ·	- 8	(250 µm	יי ו)					
D80 - 800 (2.500 μm) 07B - 128 (15	5.625 µm)			•						
PRG - Programmable (preset to 1 μ m)										
For DPI resolution see <u>Table of available reso</u>	olutions.									
Minimum edge separation										
IA, IB and IC:		AV:								
K - 0.07 μs (15 MHz) E - 4 μs (0.25 MHz)		A - N/A								
A - 0.12 µs (8 MHz) F - 5 µs (0.2 MHz) P - 0.5 µs (0.2 MHz) C - 10 µs (0.1 MHz)										
C - 1 μ s (1 MHz) G - 10 μ s (0.1 MHz) H - 20 μ s (0.05 MHz)	The cu	ustomer's c	ontro	ller must	support	: the				
D - 2 µs (0.5 MHz)	selecte	ed edge se	eparat	ion time	even if	the				
	encod	er is used k	below	the maxi	mum sp	eed.				
Reference mark sensor										
A - With reference mark sensor Magnetic scale or ring must be ordered with re	ference mar	k If require	the	over foil c	an ha inst	alled over				
the magnetic scale.	inerence mar	K. II Tequilet	i, the t			alleu over				
B - Without reference mark sensor										
C - Without reference mark sensor but with	periodic r	eference in	npulse	e as per s	cale pito	ch (every	,			
2 mm)										
Reference periods correspond to pole length o	f magnetisat	ion. Magneti	ic scale	or ring m	ust be orc	lered with	l			
no reference mark.										
Cable length										
10 - 1.0 m (standard)		:								
(e.g. 13 - 1.3 m cable or 13 - 13 m cable if specia	al option UM	is chosen)								
Connector										
A - 9 pin D type plug	- 15 pin	n HD type p	lug							
D - 15 pin D type plug	15 pin	n D type plu	Ig							
E - 9 pin CPC connector	• - 9 pin l	D type plug	I							
F - Flying lead, no connector	J - 7 pin l	DIN EN601	30-9 p	lug						
Special requirements										
00 - No special requirements (standard) 19	- Stainles	ss steel hou	using							
02 - Shortened reaction time 40	- Protect	ive stainles	s-stee	el tube fo	r cable					
05 - For DPI resolution 0N	I - Cable le	ength in m	eters							
07 - Additional alarm output4N40Naturational alarm output	I - Protect	ive stainles	s-stee	el tube an	d cable i	in meters	5			
10 - Not potted, protected to IP50 72	- Additio	mai alarm c	output	and sho	rtened r	esponse	ume			

Not all part number combinations are valid. Please refer to the table of available combinations on the next page for available options.



	Series	Output type	Interpolation factor	Minimum edge separation	Reference mark	Cable length	Connector	Special requirements
I			PRG**	А				
IC		xxx*	K/A/B/C/D/E/ F/G/H	A/B/C		A** / D / E / H / F / U**		
	IC	04B	A/B/C/D/E/F /G/H	D / C				
	03B	B/C/D/E/F/ G/H	вис			00 / 02/ 05 / 07 / 10 / 19 / 40 /		
	LM10 IA		xxx*	K/A/B/C/D/E/ F/G/H	A/B/C		A** / D / H / F / U**	0M / 4M
		IA	04B	A/B/C/D/E/F /G/H	, D (C	10***		
		03B	B/C/D/E/F/ G/H	вис				
			xxx*	K/A/B/C/D/E/ F/G/H	A/B/C			
	IB	IB	04B	A/B/C/D/E/F /G/H	B / C	B/C	A/F/U	00 / 05 / 10 / 19 / 40 / 0M / 4M
			03B	B/C/D/E/F/ G/H				
		AV	000	A	A/B/C		A/L/P/F	

Table of available combinations

*See chapter **<u>Available resolutions</u>** for available interpolation factors.

**Not available with special option 07.

***See the Output Type section for the max cable lenght for each output type.

For the part numbering of the MS incremental magnetic scale or the MR radial and axial incremental magnetic ring, refer to the data sheets **MSD01**, **MR02D02** and **MR01D01** at **<u>RLS Media center</u>**.

Available resolutions

Table of available resolutions

		Resolution			
Part number	Interpolation factor	In µm with 2 mm poles	CPI (counts per inch 2,032 mm) ¹⁾	DPI (pulse per inch 2,032 mm) ²⁾	
13B	2 ¹³	0.244140625	102,400	25,600	
12B	2 ¹²	0.48828125	51,200	12,800	
11B	211	0.9765625	25,600	6,400	
001	2000	1	25,000	6,250	
1D6	1600	1.25	20,000	5,000	
10B	210	1.953125	12,800	3,200	
002	1000	2	12,500	3,125	
D80	800	2.5	10,000	2,500	
09B	2 ⁹	3.90625	6,400	1,600	
D50	500	4	6,250	1,562.5	
005	400	5	5,000	1,250	
D32	320	6.25	4,000	1,000	
08B	2 ⁸	7.8125	3,200	800	
010	200	10	2,500	625	
D16	160	12.5	2,000	500	
07B	27	15.625	1,600	400	
020	100	20	1,250	312.5	
D08	80	25	1,000	250	
06B	26	31.25	800	200	
050	40	50	500	125	
05B	25	62.5	400	100	
04B	24	125	200	50	
03B	2 ³	250	100	25	

Resolutions calculation



PPR – Pulses per revolution

Resolution [PPR] = $\frac{\text{Resolution [CPR]}}{4}$

Resolutions calculation for CPI/DPI

Resolution [μ m] = $\frac{\text{Pole length } [\mu m]}{\text{Interpolation factor}} = \frac{2032}{\text{Interpolation factor}}$

Resolution [CPI] = $\frac{\text{Inch [µm]}}{\text{Resolution [µm]}}$ =

= $\frac{\text{Inch [}\mu\text{m}\text{]} \times \text{Interpolation factor}}{\text{Pole length [}\mu\text{m}\text{]}} =$

 $= \frac{25400 \times \text{Interpolation factor}}{2032}$

Resolution [DPI] = $\frac{CPI}{4}$

*See pole numbers in the MR01D01 or MR02D02 data sheet at **RLS Media center.**







Accessories



USB encoder interface **E201-9Q**

(Compatible only with LM10IC)



Programmable interface <u>UPRG01</u>

(Compatible only with LM10IC)



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Document issues

Date	Page	Description
13. 10. 2022	General	New design, data amended

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